

## BEHAVIOR OF SOLUTIONS OF NONLINEAR FUNCTIONAL VOLTERRA INTEGRO-DIFFERENTIAL EQUATIONS WITH MULTIPLE DELAYS

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**ABSTRACT.** The authors consider the nonlinear functional Volterra integro-differential equation with multiple delays

$$x'(t) = -a(t)x(t) + \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds.$$

They give sufficient conditions so that solutions are bounded, belong to  $L^1$ , or belong to  $L^2$ . They also prove the stability and global asymptotic stability of the zero solution. Their technique of proof involves defining appropriate Lyapunov functionals.

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### 1. Introduction

In 2009, Becker [4] considered the scalar linear Volterra integro-differential equation

$$x'(t) = -a(t)x(t) + \int_0^t b(t, s)x(s) ds$$

for  $t \geq 0$ , where  $a$  and  $b$  are real-valued functions that are continuous on their respective domains. He discussed the asymptotic behavior of solutions of this equation by using Lyapunov functionals.

In this paper, we consider the scalar nonlinear functional Volterra integro-differential equation with multiple delays

$$(1.1) \quad x'(t) = -a(t)x(t) + \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds,$$

where  $a$ ,  $f$  and  $b_i$  are real-valued and continuous functions on their respective domains. We will investigate various questions about the behavior of solutions of (1.1) including their boundedness, integrability, and the stability and global asymptotic stability

of the zero solution. Our results differ from those currently in the literature (see, [3–12, 14, 16–20] and the references therein).

We let  $L^1[0, \infty)$  denote the set of all real-valued functions  $g$  for which  $\int_0^\infty |g(s)|ds < \infty$  and  $L^2[0, \infty)$  denote the set of all real-valued functions  $h$  that are square integrable on  $[0, \infty)$ , i.e.,  $\int_0^\infty |h(s)|^2 ds < \infty$ .

## 2. Main Results

First, we establish sufficient conditions for all solutions of Eq. (1.1) to be bounded and belong to  $L^2[0, \infty)$ . Then, under additional conditions, we show that the solutions tend to zero as  $t \rightarrow \infty$  as well. Our covering assumptions on the functions in equation (1.1) are as follows. Let  $\Omega := \{(t, s) : 0 \leq s \leq t < \infty\}$  and let  $\tau = \max_{1 \leq i \leq n} \tau_i$ . Assume that:

- (H1) The functions  $a : [0, \infty) \rightarrow [0, \infty)$ ,  $f_i : \mathbb{R} \rightarrow \mathbb{R}$ , and  $b_i : \Omega \rightarrow \mathbb{R}$  are continuous for each  $i = 1, 2, \dots, n$ ;
- (H2) there exists a constant  $\alpha > 0$  such that  $|f_i(x)| \leq \alpha|x|$  for all  $x \in \mathbb{R}$  and  $i = 1, 2, \dots, n$ .

Our first result shows that solutions of equation (1.1) are bounded and the zero solution is stable.

**Theorem 2.1.** *Assume conditions (H1)–(H2) hold. If*

$$(2.1) \quad a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \geq 0$$

for all  $t \geq t_0 - \tau \geq 0$  and

$$(2.2) \quad a(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| ds \geq 0$$

for all  $t \geq 0$ , then all solutions of equation (1.1) are bounded and the zero solution of (1.1) is stable.

*Proof.* For any  $t_0 \geq 0$  and initial function  $\varphi \in C[t_0 - \tau, t_0]$ , let  $x(t) = x(t, t_0, \varphi)$  denote the solution of Eq. (1.1) on  $[t_0 - \tau, \infty)$  such that  $x(t) = \varphi(t)$  on  $[t_0 - \tau, t_0]$ . Define the functional

$$V : [0, \infty) \times C[0, \infty) \rightarrow [0, \infty)$$

by

$$(2.3) \quad V(t, \psi(\cdot)) = \psi^2(t) + \int_0^t \left\{ a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \right\} \psi^2(s) ds.$$

From (2.1), it is clear that

$$(2.4) \quad V(t, \psi(\cdot)) \geq \psi^2(t) \quad \text{for all } t \geq t_0 - \tau.$$

Differentiating (2.3), we obtain

$$\begin{aligned}
V'(t) &= \frac{d}{dt}V(t, x(t)) = 2x(t)x'(t) + a(t)x^2(t) - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) \\
&\quad - \int_0^t \sum_{i=1}^n \alpha |b_i(t, s)| x^2(s) ds \\
&= 2x(t) \left[ -a(t)x(t) + \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds \right] + a(t)x^2(t) \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&= -a(t)x^2(t) + 2x(t) \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&\leq -a(t)x^2(t) + 2|x(t)| \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, s)| |x(s)| ds \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&\leq -a(t)x^2(t) + \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| (x^2(t) + x^2(s)) ds \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&= -a(t)x^2(t) + \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| ds x^2(t) \\
&\quad + \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x^2(s) ds \\
&= -a(t)x^2(t) + \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| ds x^2(t) \\
&\quad - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du x^2(t) \\
&= - \left\{ a(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| ds + \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du \right\} x^2(t).
\end{aligned}$$

Hence,

$$(2.5) \quad V'(t) \leq - \left\{ a(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| ds + \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du \right\} x^2(t)$$

for all  $t \geq 0$ . From condition (2.2), we see that

$$V'(t) \leq 0 \quad \text{for } t \geq t_0.$$

This, together with (2.4), shows that all solutions of (1.1) are bounded, and in fact,

$$(2.6) \quad x^2(t) \leq V(t) \leq V(t_0)$$

for all  $t \geq t_0$ . From the above estimate and the fact that

$$V(t_0) = \varphi^2(t_0) + \int_0^{t_0} \left\{ a(s) - \sum_{i=1}^n \int_{s-\tau_i}^{t_0} \alpha |b_i(t, u)| du \right\} \varphi^2(s) ds \leq |\varphi|_{t_0}^2 B_0,$$

where

$$B_0 = 1 + \int_0^{t_0} \left\{ a(s) - \sum_{i=1}^n \int_{s-\tau_i}^{t_0} \alpha |b_i(t, u)| du \right\} ds,$$

we obtain

$$(2.7) \quad |x(t)| \leq |\varphi|_{t_0} \sqrt{B_0}$$

for all  $t \geq t_0 \geq s - \tau$ . It immediately follows that the zero solution of (1.1) is stable, i.e., for any  $\varepsilon > 0$ , choose  $\delta = \varepsilon / \sqrt{B_0}$  and so for  $\varphi \in C[t_0 - \tau, t_0]$  with  $|\varphi|_{t_0} < \delta$ , we have

$$(2.8) \quad |x(t)| \leq \delta \sqrt{B_0} = \varepsilon.$$

□

In our next theorem, we show that solutions are square integrable, i.e., they belong to the class  $L^2$ .

**Theorem 2.2.** *If in addition to conditions (H1)–(H2) and (2.1)–(2.2), there exist  $t_1 \geq t_0$  and a constant  $k > 0$  such that either*

$$(2.9) \quad a(t) - \sum_{i=1}^n \int_0^t \alpha |b_i(t, u)| du \geq k \quad \text{for } t \geq t_1,$$

or

$$(2.10) \quad a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \geq k \quad \text{for } t \geq s - \tau \geq t_0,$$

then every solution of Eq. (1.1) belongs to  $L^2[0, \infty)$ .

*Proof.* From Theorem 2.1, any solution  $x(t)$  of (1.1) is bounded and satisfies (2.5) and (2.6). If (2.9) holds, then from (2.5) we have

$$V'(t) \leq -kx^2(t)$$

for  $t \geq t_1$ . Integrating, we obtain

$$k \int_{t_1}^t x^2(s) ds \leq V(t_1) - V(t) \leq V(t_1)$$

so  $x \in L^2[0, \infty)$ .

If (2.10) holds, then from the definition of  $V$ , we have

$$(2.11) \quad x^2(t) + k \int_{t_1}^t x^2(s) ds \leq V(t) \leq V(t_1),$$

so again  $x \in L^2[0, \infty)$ . This proves the theorem.  $\square$

In order to show that the zero solution is globally asymptotically stable, we will have to require an additional condition.

**Theorem 2.3.** *Let conditions (H1)–(H2), (2.1)–(2.2), and either (2.9) or (2.10) hold. If there is a constant  $K > 0$  such that*

$$(2.12) \quad a(t) + \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, s)| ds \leq K$$

for all  $t \geq t_1$ , then the zero solution of (1.1) is globally asymptotically stable.

*Proof.* By Theorem 2.2, we have that every solution belongs to  $L^2[0, \infty)$ . From (1.1) and (2.7), we have

$$(2.13) \quad |x'(t)| \leq a(t) |\varphi|_{t_0} \sqrt{B_0} + \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, s)| ds |\varphi|_{t_0} \sqrt{B_0}$$

$$(2.14) \quad \leq |\varphi|_{t_0} \sqrt{B_0} K,$$

so  $x'(t)$  is bounded. This together with the fact that  $x \in L^2[0, \infty)$  implies that  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ . Thus, the zero solution of (1.1) is globally asymptotically stable.  $\square$

As simple examples such as  $x(t) = \frac{1}{t+1}$  show, a function belonging to  $L^2$  may not belong to  $L^1$ . We next develop conditions under which solutions of (1.1) do in fact belong to the class  $L^1[0, \infty)$ .

**Theorem 2.4.** *If (2.1) holds, then all solutions of (1.1) are bounded and the zero solution of (1.1) is stable. If, in addition, there are constants  $k_1 > 0$  and  $0 \leq \beta < 1$  such that*

$$(2.15) \quad a(t) \geq k_1$$

and

$$(2.16) \quad \beta a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \geq 0,$$

then all solutions of (1.1) belong to  $L^1[0, \infty)$ . Moreover, if (2.12) also holds, then  $x \in L^2[0, \infty)$  and the zero solution of (1.1) is globally asymptotically stable.

*Proof.* Define the functional

$$V_1 : [0, \infty) \times C[0, \infty) \rightarrow [0, \infty)$$

by

$$(2.17) \quad V_1(t, \psi(\cdot)) = |\psi(t)| + \int_0^t \left\{ a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \right\} |\psi(s)| ds.$$

As described in [15, p. 26] and pointed out by Becker [4], for a continuously differentiable function  $h(t)$ ,  $|h(t)|$  has a right derivative  $D_r$  given by

$$D_r |h(t)| = \begin{cases} h'(t) \operatorname{sgn} h(t), & \text{if } h(t) \neq 0 \\ |h'(t)|, & \text{if } h(t) = 0. \end{cases}$$

We then have

$$\begin{aligned} D_r V_1(t) &= D_r V_1(t, x(t)) = -a(t)|x(t)| + \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds \\ &\quad + a(t)|x(t)| - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du |x(t)| \\ &\quad - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| |x(s)| ds \\ &\leq \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, s)| |x(s)| ds - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du |x(t)| \\ &\quad - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| |x(s)| ds \\ &\leq - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, s)| ds |x(t)| \\ &\leq 0. \end{aligned}$$

Now  $V_1(t) \geq |x(t)|$  by (2.1), so the boundedness of solutions and the stability of the zero solution follow as in Theorem 2.1.

Next we modify the functional in (2.17), i.e., consider

$$(2.18) \quad V_\beta(t, \psi(\cdot)) = |\psi(t)| + \int_0^t \left\{ \beta a(s) - \sum_{i=1}^n \int_{s-\tau_i}^t \alpha |b_i(t, u)| du \right\} |\psi(s)| ds.$$

Then,

$$\begin{aligned}
D_r V'_\beta(t) &= -a(t)|x(t)| + \sum_{i=1}^n \int_{t-\tau_i}^t b_i(t, s) f_i(x(s)) ds \\
&\quad + \beta a(t)|x(t)| - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du |x(t)| - \sum_{i=1}^n \int_0^t \alpha |b_i(t, s)| x(s) ds \\
&\leq -(1 - \beta)a(t)|x(t)| - \sum_{i=1}^n \int_{t-\tau_i}^t \alpha |b_i(t, u)| du |x(t)| \\
&\leq -(1 - \beta)k_1|x(t)| \\
&\leq 0
\end{aligned}$$

by (2.15). Integrating, we obtain

$$(1 - \beta)k \int_{t_0}^t |x(s)| ds \leq V_\beta(t_0) - V_\beta(t)$$

so  $x \in L^1[t_0, \infty)$ .

Now if (2.12) also holds, as in the proof of Theorem 2.3 we can easily show that  $|x'(t)|$  is bounded. This, together with the fact that  $x \in L^1[0, \infty)$  implies  $x \in L^2[0, \infty)$ , guarantees that  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ , and so the zero solution of (1.1) is globally asymptotically stable.  $\square$

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